

## Homework 1

- 1) The position of a remote controlled model boat on a pond, relative to a rectangular coordinate system with origin  $O$ , is given by

$$\mathbf{r} = (3t^2 - 12t + 5)\mathbf{i} + (4t - t^2)\mathbf{j},$$

where  $\mathbf{i}$ ,  $\mathbf{j}$  are unit vectors in the  $Ox$  and  $Oy$  directions respectively,  $t$  is time measured in seconds and distances are measured in metres.

Calculate the distance of the boat from the origin  $O$  when it comes to instantaneous rest.

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- 2) A particle has velocity  $3t(2 - t)\mathbf{j}$  where  $\mathbf{j}$  is the unit vector in the direction of motion. The time  $t$  is measured in seconds from the start of the motion and the displacement is measured in metres. Initially the particle is at the point with position vector  $3\mathbf{j}$  relative to the origin  $O$ . Calculate the distance of the particle from  $O$  when the velocity is a maximum.

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- 3) The position of a model boat  $P$ , relative to a rectangular coordinate system with origin  $O$ , is given by

$$\mathbf{r}_P = t^2\mathbf{i} + 4t\mathbf{j}$$

where  $\mathbf{i}$  and  $\mathbf{j}$  are unit vectors in the  $Ox$  and  $Oy$  directions respectively,  $t$  is the time measured in seconds and distances are measured in metres.

The acceleration of a second boat  $Q$  is given by

$$\mathbf{a}_Q = 2\mathbf{i} + (4\pi \sin 2\pi t)\mathbf{j}.$$

Given that boat  $Q$  is initially at rest, find the first two times when the boats have the same velocity.

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- 4) Relative to a rectangular coordinate system, the position of an ice skater at time  $t$  seconds is

$$\mathbf{r}(t) = \left(\frac{1}{3}t^3 - 4t^2\right)\mathbf{i} - (2t^2 - 1)\mathbf{j},$$

where  $\mathbf{i}$ ,  $\mathbf{j}$  are the unit vectors in the  $x$ ,  $y$  directions respectively and distances are measured in metres.

Find the speed of the ice skater at the instant when the acceleration is parallel to the  $y$ -axis.

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- 5) The velocity of an ice skater relative to a rectangular coordinate system with origin  $O$ , is given by

$$\mathbf{v} = 3(t^2 - 4t + 2)\mathbf{i} + 4\mathbf{j},$$

where  $\mathbf{i}$ ,  $\mathbf{j}$  are unit vectors in the  $Ox$  and  $Oy$  directions,  $t$  seconds is the time and the speed is measured in  $\text{m s}^{-1}$ . Initially the skater has position vector  $-4\mathbf{j}$ .

- (a) Find the time at which the acceleration is instantaneously equal to zero. 2
- (b) Calculate the distance of the skater from  $O$  when the acceleration is instantaneously equal to zero. 4